

$$\textcircled{1} \quad V_1' = -\frac{1}{5} V_1$$

$$V_1' = \frac{m_1 - m_2}{m_1 + m_2} \cdot V_1 \Rightarrow -\frac{V_1}{5} = \frac{m_1 - m_2}{m_1 + m_2} \cdot V_1 \Rightarrow$$

$$-m_1 - m_2 = 5m_1 - 5m_2 \Rightarrow 4m_2 = 6m_1 \Rightarrow$$

$$\frac{m_2}{m_1} = \frac{6}{4} = \frac{3}{2} \quad \textcircled{a}$$

\textcircled{2}

$$\alpha \% = \frac{\frac{1}{2} m_2 v_2'^2}{\frac{1}{2} m_1 v_1'^2} \cdot 100\% \Rightarrow$$

$$\frac{36}{100} = \frac{\frac{1}{2} m_2 \frac{4m_1^2}{(m_1+m_2)^2} \cdot v_1^2}{\frac{1}{2} m_1 v_1'^2} \cdot 100\% \Rightarrow$$

$$0,36 = \frac{4m_1 \cdot m_2}{(m_1+m_2)^2} \Rightarrow$$

$$\frac{4m_1 m_2}{(m_1+m_2)^2} = \frac{9}{25} \Rightarrow 9m_2^2 + 9m_1^2 + 18m_1 m_2 = 100m_1 m_2$$

$$9m_2^2 - 82m_1 m_2 + 9m_1^2 = 0$$

$$\Delta = b^2 - 4ac = 24m_1^2 - 4 \cdot 9 \cdot 9m_1^2 \Rightarrow \Delta = 6400m_1^2$$

$$m_2 = \frac{82m_1 \pm 80m_1}{18} \quad \begin{cases} m_2 = \frac{m_1}{9} \\ m_2 = 9m_1 \end{cases} \quad \textcircled{b}$$



$$v = \frac{m_A v_A}{m_A + m_B}$$

$$\alpha \% = \frac{\frac{1}{2} m_A v_A'^2 - \frac{1}{2} (m_A + m_B) v^2}{\frac{1}{2} m_A v_A'^2} \Rightarrow$$

$$\alpha\% = \frac{\frac{1}{2} m_A v_A^2 - \frac{1}{2} \frac{m_A^2 v_A^2}{m_A + m_B}}{\frac{1}{2} m_A v_A^2} \Rightarrow$$

$$\alpha\% = 1 - \frac{m_A}{m_A + m_B} \Rightarrow \alpha\% = \frac{m_A + m_B - m_A}{m_A + m_B} \Rightarrow$$

$$\frac{25}{100} = \frac{m_B}{m_A + m_B} \quad \textcircled{1}$$

$$m_B \xrightarrow{v_B} \textcircled{0} \quad \textcircled{0} \xrightarrow{v}$$

$$m_B v_B = (m_A + m_B) v$$

$$\beta\% = \frac{\frac{1}{2} m_B v_B^2 - \frac{1}{2} (m_A + m_B) v^2}{\frac{1}{2} m_B v_B^2} \Rightarrow$$

$$\beta\% = \frac{m_B v_B^2 - (m_A + m_B) \frac{m_B^2 v_B^2}{(m_A + m_B)^2}}{m_B v_B^2}$$

$$\beta\% = 1 - \frac{m_B}{m_A + m_B} \Rightarrow \beta\% = \frac{m_A}{m_A + m_B} \quad \textcircled{2}$$

$$\text{Ans (1)} \Rightarrow m_A + m_B = 4m_B \Rightarrow m_A = 3m_B \quad \text{(3)}$$

$$(2) \text{ (3)} \quad \beta\% = \frac{3m_B}{4m_B} = 0.75 \quad \textcircled{3}$$

$$\textcircled{4} \quad m_1 = 2 \text{ kg}$$

$$m_2 = 3 \text{ kg}$$

$$v_1 = 4 \text{ m/s}$$

$$v_2 = 2 \text{ m/s}$$

$$P_{\text{avg}}^2 = P_1^L + P_2^L \Rightarrow$$

$$P_{\text{SDS}}^2 = 64 + 36 = 100 \Rightarrow P_{\text{SDS}} = 10 \Rightarrow$$

$$m_2 v_K = 10 \Rightarrow v_K = 2 \text{ m/s}$$

$$K_{006} = \frac{P_{6062}}{2M_0} = \frac{100}{2 \cdot 5} = 10$$

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⑤

$$m_1 = m$$

$$m_2 = m$$

$$m_3 = 3m$$



$$v_3' = \frac{2m_2}{m_2 + m_3} \cdot v_2' \Rightarrow v_3 = \frac{2m}{4m} \cdot v_1 \Rightarrow$$

$$\boxed{\frac{v_3}{v_1} = \frac{1}{2}}$$

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⑥

$$m = 1,5 \text{ kg}$$

$$R = 1,8 \text{ m}$$

$$M = 3 \text{ kg}$$

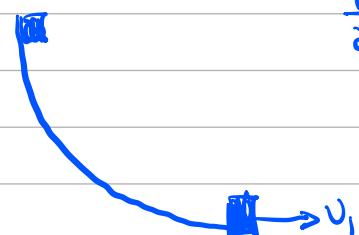
$$L = 1,6 \text{ m}$$

a) kinetik:

$$\Delta K = \delta M \Rightarrow$$

$$\frac{1}{2} M v_1^2 = M g R \Rightarrow$$

$$v_1 = \sqrt{2gR}$$



$$\boxed{v_1 = 6 \text{ m/s}}$$

b) hypot

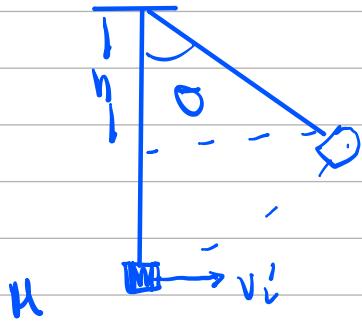


$$U_1' = \frac{m-m}{m+m} \cdot v_1 = \frac{-1,5}{4,5} \cdot 6 = -2 \text{ m/s}$$

$$U_2' = \frac{2m}{m+m} \cdot v_1 = \frac{3}{4,5} \cdot 6 = 4 \text{ m/s}$$

$$\alpha \% = \frac{\frac{1}{2} N \frac{v_2'^2}{2}}{\frac{1}{2} M \cdot v_1'^2} \cdot 100 \% = \frac{3 \cdot 4^2}{1,5 \cdot 36} = \frac{32}{36} = 88,8\%$$

d)

ADNE

$$\frac{1}{2} \mu v_1'^2 + 0 = 0 + Mg(l-h)$$

$$B = 10(1,6-h)$$

$$B = 16 - 10h \Rightarrow 10h = 8 \Rightarrow$$

$$h = 0.8.$$

$$\text{Ach } \tan \theta = \frac{h}{l} = \frac{0.8}{1.6} = \frac{1}{2}$$

d)  $\delta F_R = F_{RN} \Rightarrow T_v - Mg = M \frac{v_1'^2}{l} \Rightarrow$

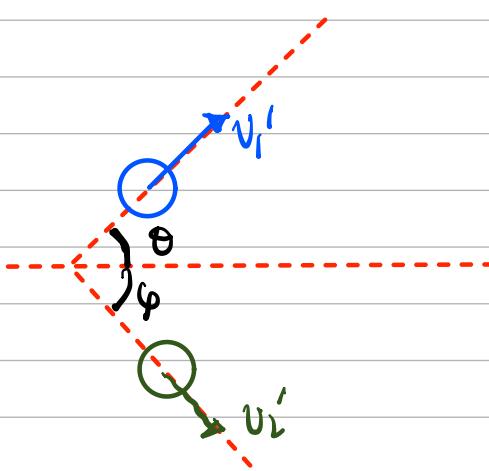
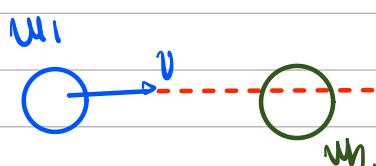
$$T_v = 30 + 3 \frac{16}{1.6} \Rightarrow \boxed{T_v = 60 \text{ N}}$$

(f)

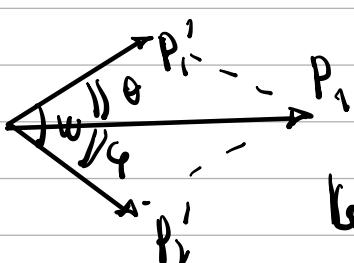
$$m_1 = m_2 = m = 2 \text{ kg}$$

$$v_1 = 2 \text{ m/s}$$

$$\theta = 60^\circ$$

ADAO

$$\vec{P}_{\text{pp}} = \vec{P}_{\mu \mu} \Rightarrow \\ \vec{P}_i = \vec{P}_i' + \vec{P}_i'$$



$$P_i^2 = P_i'^2 + P_i'^2 + 2P_i' P_i' \cos \theta - 2P_i' P_i' \cos \theta \Rightarrow \\ v_i'^2 = v_1'^2 + v_2'^2 + 2v_1' v_2' \cos \theta \quad (1)$$

$$k_{\text{el}} n_{\text{pp}} v = k_{\text{el}} \mu_{\text{kin}} \Rightarrow$$

$$\frac{1}{2} \mu_1 v_1'^2 + \frac{1}{2} \mu_2 v_2'^2 \Rightarrow$$

$$v_i'^2 = v_1'^2 + v_2'^2 \quad (2)$$

$$(1) \xrightarrow{(2)} 2v_1' v_2' \cdot \cos \theta = 0 \quad \text{da} \quad \theta \neq 90^\circ \Rightarrow \theta = 0^\circ \Rightarrow v = \frac{l}{2}$$

$$B. \text{ a) } \frac{p_1'}{p_1} = \frac{U_1}{U_2} \Rightarrow U_2 \cdot 30^\circ = \frac{p_1'}{p_1} \Rightarrow \frac{1}{2} = \frac{U_1 U_2'}{U_1 U_2} \Rightarrow$$

$$2D_1' = 2 \Rightarrow D_1' = 1 \text{ m/s}$$

$$\text{Ansl (2)} \quad V_2' = a^2 - l^2 \Rightarrow V_2' = \sqrt{3} \text{ m/s}$$

$$b) \Delta K_1 = K_1 \mu_{\text{min}} - K_1 \mu_{\text{ref}} \Rightarrow \Delta K_1 = \frac{1}{2} U_1 V_1'^2 - \frac{1}{2} U_1 V_1^2 = \\ = \frac{1}{2} 2 (1 - 4) \Rightarrow \Delta K_1 = -3 J$$

(B)

$$U_1 = 2 \text{ m/s}$$

$$V_1 = 20 \text{ m/s}$$

$$\varphi = 60^\circ$$

$$U_2 = 3 \text{ m/s}$$



$$a) \because 2 \text{ m/s} \quad F_x \text{ ref} = F_x \text{ min} \Rightarrow W_1 V_1 \cdot \sin 60^\circ = (W_1 + W_2) V \Rightarrow \\ 2 \cdot 20 \cdot \frac{1}{2} = 5 V \Rightarrow V = 4 \text{ m/s}$$

$$b) Q = E_{\text{kinetic}} = K_{\text{ref}} \text{ ref} - K_{\text{ref}} \mu_{\text{min}} = \frac{1}{2} U_1 V_1^2 - \frac{1}{2} (U_1 + U_2) V^2 \\ Q = \frac{1}{2} \cdot 2 \cdot 400 - \frac{1}{2} \cdot 5 \cdot 16 \Rightarrow Q = 360 \text{ J}$$

$$d) \alpha \% = \frac{\frac{1}{2} U_2 V}{\frac{1}{2} U_1 V_1^2} \cdot 100 \% = \frac{3 \cdot 42}{2 \cdot 400} = \frac{48}{2 \cdot 400} = 0,06 \\ \text{d.h. } 6 \%$$

$$e) \Delta P_{\text{Ges}} = \Delta P_{\text{Ges}, y} = \cancel{F_y}_{\text{ref}} - F_y \text{ ref} \Rightarrow$$

$$\Delta P_{\text{Ges}} = - U_1 \cdot V_1 \cdot \sin 60^\circ = - 2 \cdot 20 \cdot \frac{\sqrt{3}}{2} \Rightarrow \Delta P_{\text{Ges}} = - 20 \sqrt{3} \text{ N}$$

$$e) \Delta F_y = \frac{\Delta P_{\text{Ges}, y}}{\Delta t} \Rightarrow U_2 g - N = \frac{\Delta P_{\text{Ges}}}{\Delta t} \Rightarrow$$

$$N = 50 + \frac{20\sqrt{3}}{10^{-2}\sqrt{3}} \Rightarrow$$

$$N = 2050 N$$

⑨  $m_1 = 3m$   
 $m_2 = m$   
 $v_0$

$$P_{1p} = P_{2m} \Rightarrow m_1 v_0 - m_2 v_0 = m_1 v'_1 \cdot \cos \theta$$

$$3m v_0 - m v_0 = m v'_1 \cos \theta$$

$$2m v_0 = 3m v'_1 \cdot \cos \theta \Rightarrow$$

$$\cos \theta = \frac{2v_0}{3v'_1} \quad ①$$

$$P_{ymin} = P_{ymax} \Rightarrow 0 = m_1 \cdot v'_1 \sin \theta - m_2 v'_2 \Rightarrow$$

$$m v'_2 = 3m v'_1 \sin \theta \Rightarrow$$

$$\sin \theta = \frac{v'_2}{3v'_1} \quad ②$$

$$k_{dyn} = k_{kin} \Rightarrow \frac{1}{2} 3m v_0^2 + \frac{1}{2} m v_0^2 = \frac{1}{2} 3m v'_1^2 + \frac{1}{2} m v'_2^2$$

$$4v_0^2 = 3v'_1^2 + v'_2^2 \quad ③$$

Analog (1) by (2):

$$\begin{aligned} \sin^2 \theta &= \frac{4v_0^2}{9v'_1^2} \\ \sin^2 \theta &= \frac{v'_2^2}{9v'_1^2} \end{aligned} \quad \left. \begin{array}{l} \Rightarrow 1 = \frac{4v_0^2}{9v'_1^2} + \frac{v'_2^2}{9v'_1^2} \Rightarrow \\ \Rightarrow 1 = \frac{4v_0^2 + v'_2^2}{9v'_1^2} \end{array} \right.$$

$$1 = \frac{4v_0^2 + v'_2^2}{9v'_1^2} \Rightarrow 9v'_1^2 = 4v_0^2 + v'_2^2 \Rightarrow v'_2^2 = 9v'_1^2 - 4v_0^2 \quad ④$$

$$4v_0^2 = 3v'_1^2 + 9v'_1^2 - 4v_0^2 \Rightarrow 8v_0^2 = 12v'_1^2 \Rightarrow$$

$$v'_1 = v_0 \sqrt{\frac{2}{3}}$$

Analog (3)

$$4v_0^2 = 3v_0^2 \frac{2}{3} + v'_2^2 \Rightarrow v'_2 = v_0 \sqrt{2}$$

Analog (2)

$$\sin \theta = \frac{v_0 \sqrt{2} \cdot \sqrt{3}}{3v_0 \sqrt{2}} = \frac{\sqrt{3}}{3}$$

