

Πύλο! Μεταβολές στην Α.Α.Τ.

- $\frac{dx}{dt} = v = \omega A \cos(\omega t + \phi_0)$
- $\frac{dv}{dt} = a = -\omega^2 A \sin(\omega t + \phi_0)$
- $\frac{dp}{dt} = \Sigma F = -Dx = -\underbrace{\omega^2}_{k/m} A \sin(\omega t + \phi_0)$

ΘΜΚΕ:
 $\Delta K = W_{\text{ext}} = W_{\Sigma F}$
 $d(\Theta \text{ΜΚΕ}):$
 $dk = dW_{\Sigma F}$

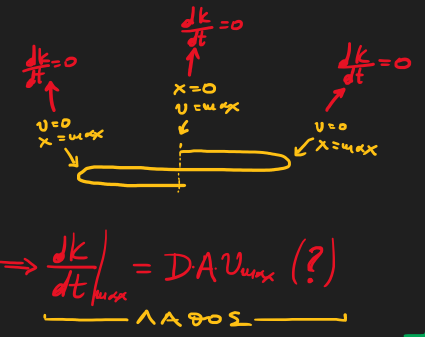
• $\frac{dk}{dt} \stackrel{\Theta \text{ΜΚΕ}}{=} \frac{dW_{\Sigma F}}{dt} = \frac{\Sigma F \cdot dx}{dt} = \Sigma F \cdot v = -Dx \cdot v = -\omega^2 A \sin(\omega t + \phi_0) \cdot \omega A \cos(\omega t + \phi_0) =$



Γιόγγω του ρυθμισμού ($E = K + U$)

• $\frac{dE}{dt} = 0$ (γιατί $E = \text{const}$)

• $\frac{dE}{dt} = 0 \Rightarrow \frac{d(K+U)}{dt} = 0 \Rightarrow \frac{dk}{dt} + \frac{dU}{dt} = 0 \Rightarrow \frac{dU}{dt} = -\frac{dk}{dt} = -(-Dx \cdot v) = Dx \cdot v = \dots = \omega^2 A^2 \sin(\omega t + \phi_0) \cdot \cos(\omega t + \phi_0) \xrightarrow{\phi_0=0} \frac{dU}{dt} = \omega^2 A^2 \sin(2\omega t) = \frac{\omega^3 A^2}{2} \cdot 2 \cos(2\omega t)$

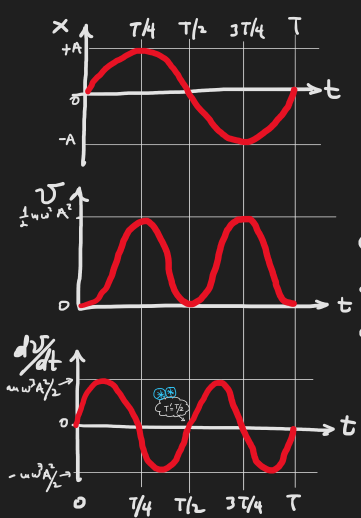


$\frac{dk}{dt} \Big|_{\text{max}} = \frac{\omega^3 A^2}{2} \hat{=} \frac{DA v_{\text{max}}}{2}$

$x = A \cdot \sin \omega t$

$U = \frac{1}{2} D x^2 = \frac{1}{2} \omega^2 A^2 \cdot \sin^2 \omega t$

$\frac{dU}{dt} = \frac{\omega^3 A^2}{2} \cdot 2 \sin \omega t \cos \omega t$



$U = \omega A \cos \omega t$

$K = \frac{1}{2} m v^2 = \frac{1}{2} m \omega^2 A^2 \cos^2 \omega t$

$\frac{dK}{dt} = -\frac{\omega^3 A^2}{2} \cdot 2 \sin(2\omega t)$

